

# Package ‘vntrs’

May 7, 2026

**Title** Variable Neighborhood Trust Region Search

**Version** 0.2.1

**Description** Implements the variable neighborhood trust region search (VNTRS) algorithm for nonlinear global optimization, following Bierlaire et al. (2009) “A Heuristic for Nonlinear Global Optimization” <[doi:10.1287/ijoc.1090.0343](https://doi.org/10.1287/ijoc.1090.0343)>. The method combines neighborhood exploration with a trust-region framework to search the solution space efficiently. It can terminate a local search early when the iterates converge toward a previously visited local optimum or when further improvement within the current region is unlikely. The algorithm can also be used to identify multiple local optima.

**URL** <https://loelschlaeger.de/vntrs/>

**BugReports** <https://github.com/loelschlaeger/vntrs/issues>

**License** GPL-3

**Encoding** UTF-8

**RoxygenNote** 7.3.3

**Imports** checkmate, oeli (>= 0.7.5), Rcpp

**LinkingTo** Rcpp, RcppArmadillo

**Suggests** testthat (>= 3.0.0)

**Config/testthat/edition** 3

**NeedsCompilation** yes

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**Repository** CRAN

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 vntrs

*Variable neighborhood trust region search*


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### Description

Run the variable neighborhood trust region search algorithm.

### Usage

```
vntrs(
  f,
  npar,
  minimize = TRUE,
  init_runs = 5L,
  init_min = -1,
  init_max = 1,
  init_iterlim = 20L,
  neighborhoods = 5L,
  neighbors = 5L,
  beta = 0.05,
  iterlim = 100L,
  tolerance = 1e-06,
  inferior_tolerance = 1e-06,
  time_limit = NULL,
  cores = 1L,
  lower = NULL,
  upper = NULL,
  collect_all = FALSE,
  quiet = TRUE
)
```

### Arguments

f	[function] A function that accepts a numeric parameter vector and returns either <ul style="list-style-type: none"> <li>• a numeric objective value, or</li> <li>• a list with value and optional gradient and hessian components.</li> </ul> Missing derivatives are approximated by finite differences.
npar	[integer(1)] The number of parameters of f.
minimize	[logical(1)] If TRUE, minimize f; otherwise, maximize it.
init_runs	[integer(1)] Number of random starting points for the initialization stage.

<code>init_min, init_max</code>	[numeric(1)] Lower and upper bounds for the uniform initialization range.
<code>init_iterlim</code>	[integer(1)] Maximum trust-region iterations during initialization.
<code>neighborhoods</code>	[integer(1)] Number of neighborhood expansions to try.
<code>neighbors</code>	[integer(1)] Number of trial points sampled in each neighborhood.
<code>beta</code>	[numeric(1)] Non-negative scaling factor for neighborhood expansion.
<code>iterlim</code>	[integer(1)] Maximum trust-region iterations during the main search.
<code>tolerance</code>	[numeric(1)] Minimum Euclidean distance for two optima to be treated as distinct.
<code>inferior_tolerance</code>	[numeric(1)] Maximum objective-value gap from the best known solution before a local optimum is discarded early.
<code>time_limit</code>	[numeric(1)   NULL] Optional time limit in seconds. If reached, the search stops early with a warning.
<code>cores</code>	[integer(1)] Number of CPU cores used for parallel evaluation.
<code>lower, upper</code>	[numeric(npar)   NULL] Optional lower and upper parameter bounds. Use NULL for unbounded dimensions.
<code>collect_all</code>	[logical(1)] If TRUE, keep all converged local optima and disable early stopping for optima that are inferior to the best known solution.
<code>quiet</code>	[logical(1)] If TRUE, suppress progress messages.

**Value**

A data.frame summarizing the identified optima or NULL if none could be determined.

**References**

Bierlaire et al. (2009) "A Heuristic for Nonlinear Global Optimization" [doi:10.1287/ijoc.1090.0343](https://doi.org/10.1287/ijoc.1090.0343).

**Examples**

```
rosenbrock <- function(x) 100 * (x[2] - x[1]^2)^2 + (1 - x[1])^2
vntrs(f = rosenbrock, npar = 2)
```

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