

# Definitions of $\psi$ -Functions Available in Robustbase

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## Preamble

Unless otherwise stated, the following definitions of functions are given by [Maronna et al. \(2006, p. 31\)](#), however our definitions differ sometimes slightly from theirs, as we prefer a different way of *standardizing* the functions. To avoid confusion, we first define  $\psi$ - and  $\rho$ -functions.

**Definition 1** A  $\psi$ -function is a piecewise continuous function  $\psi : \mathbb{R} \rightarrow \mathbb{R}$  such that

1.  $\psi$  is odd, i.e.,  $\psi(-x) = -\psi(x) \forall x$ ,
2.  $\psi(x) \geq 0$  for  $x \geq 0$ , and  $\psi(x) > 0$  for  $0 < x < x_r := \sup\{\tilde{x} : \psi(\tilde{x}) > 0\}$  ( $x_r > 0$ , possibly  $x_r = \infty$ ).
- 3\* Its slope is 1 at 0, i.e.,  $\psi'(0) = 1$ .

Note that ‘3\*’ is not strictly required mathematically, but we use it for standardization in those cases where  $\psi$  is continuous at 0. Then, it also follows (from 1.) that  $\psi(0) = 0$ , and we require  $\psi(0) = 0$  also for the case where  $\psi$  is discontinuous in 0, as it is, e.g., for the M-estimator defining the median.

**Definition 2** A  $\rho$ -function can be represented by the following integral of a  $\psi$ -function,

$$\rho(x) = \int_0^x \psi(x) dx, \quad (1)$$

which entails that  $\rho(0) = 0$  and  $\rho$  is an even function.

A  $\psi$ -function is called *redescending* if  $\psi(x) = 0$  for all  $x \geq x_r$  for  $x_r < \infty$ . Corresponding to a redescending  $\psi$ -function, we define the function  $\tilde{\rho}$ , a version of  $\rho$  standardized such as to attain maximum value one. Formally,

$$\tilde{\rho}(x) = \rho(x)/\rho(\infty). \quad (2)$$

Note that  $\rho(\infty) = \rho(x_r) \equiv \rho(x) \forall |x| > x_r$ .  $\tilde{\rho}$  is a  $\rho$ -function as defined in [Maronna et al. \(2006\)](#) and has been called  $\chi$  function in other contexts.

# 1 Monotone $\psi$ -Functions

Monotone  $\psi$ -functions lead to convex  $\rho$ -functions such that the corresponding M-estimators are defined uniquely.

Historically, the “Huber function” has been the first  $\psi$ -function, proposed by Peter Huber in [Huber \(1964\)](#).

## 1.1 Huber

The family of Huber functions is defined as,

$$\rho_k(x) = \begin{cases} \frac{1}{2}x^2 & \text{if } |x| \leq k \\ k(|x| - \frac{k}{2}) & \text{if } |x| > k \end{cases},$$

$$\psi_k(x) = \begin{cases} x & \text{if } |x| \leq k \\ k \operatorname{sign}(x) & \text{if } |x| > k \end{cases}.$$

The constant  $k$  for 95% efficiency of the regression estimator is 1.345.

```
> plot(huberPsi, x., ylim=c(-1.4, 5), leg.loc="topright", main=FALSE)
```

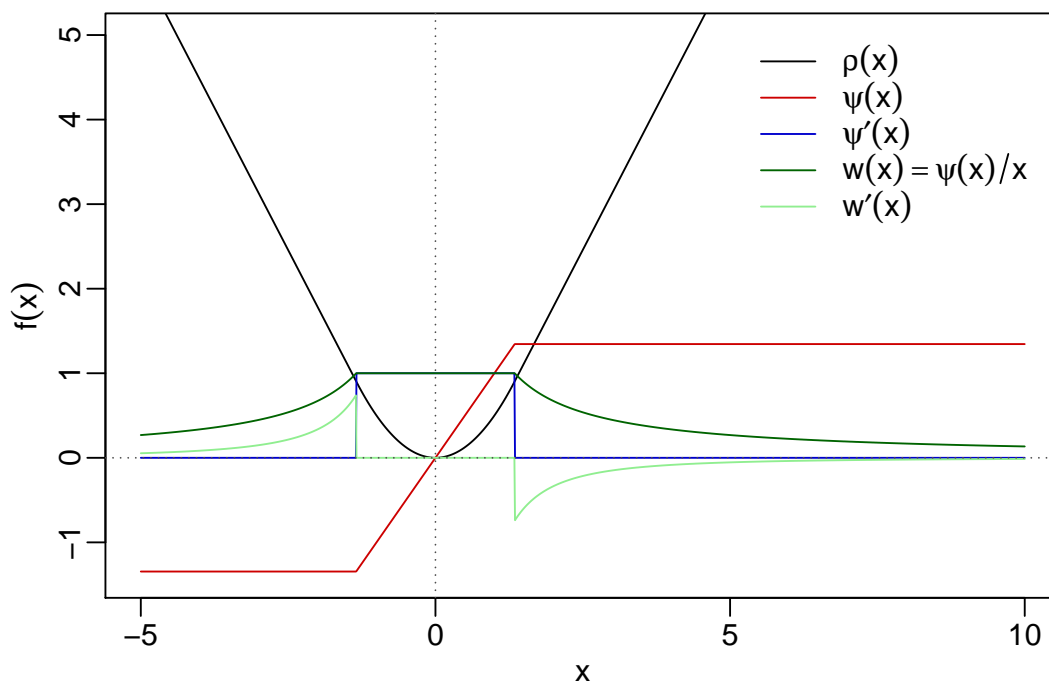


Figure 1: Huber family of functions using tuning parameter  $k = 1.345$ .

## 2 Redescenders

For the MM-estimators and their generalizations available via `lmrob()`, the  $\psi$ -functions are all redescending, i.e., with finite “rejection point”  $x_r = \sup\{t; \psi(t) > 0\} < \infty$ . From `lmrob`, the psi functions are available via `lmrob.control`,

```
> formals(lmrob.control) $ psi
c("bisquare", "lqq", "welsh", "optimal", "hampel", "ggw")
```

and their  $\psi$ ,  $\rho$ ,  $\psi'$ , and weight function  $w(x) := \psi(x)/x$ , are all computed efficiently via C code, and are defined and visualized in the following subsections.

## 2.1 Bisquare

Tukey's bisquare (aka "biweight") family of functions is defined as,

$$\tilde{\rho}_k(x) = \begin{cases} 1 - \left(1 - (x/k)^2\right)^3 & \text{if } |x| \leq k \\ 1 & \text{if } |x| > k \end{cases},$$

with derivative  $\tilde{\rho}'_k(x) = 6\psi_k(x)/k^2$  where,

$$\psi_k(x) = x \left(1 - \left(\frac{x}{k}\right)^2\right)^2 \cdot I_{\{|x| \leq k\}}.$$

The constant  $k$  for 95% efficiency of the regression estimator is 4.685 and the constant for a breakdown point of 0.5 of the S-estimator is 1.548.

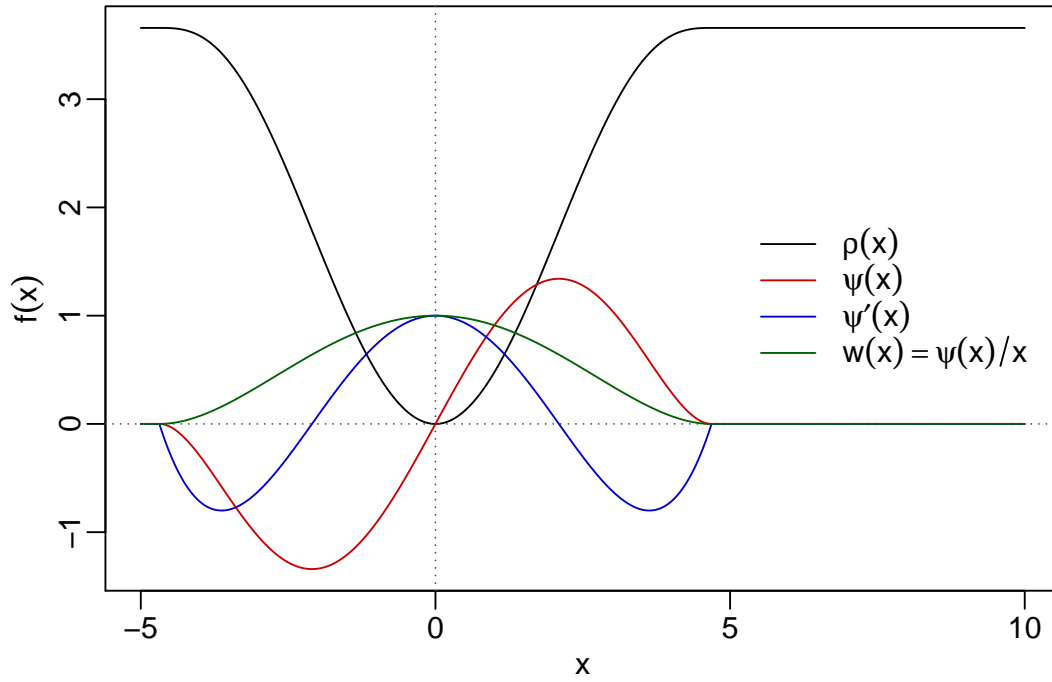


Figure 2: Bisquare family functions using tuning parameter  $k = 4.685$ .

## 2.2 Hampel

The Hampel family of functions (Hampel et al., 1986) is defined as,

$$\tilde{\rho}_{a,b,r}(x) = \begin{cases} \frac{1}{2}x^2/C & |x| \leq a \\ \left(\frac{1}{2}a^2 + a(|x| - a)\right)/C & a < |x| \leq b \\ \frac{a}{2} \left(2b - a + (|x| - b) \left(1 + \frac{r-|x|}{r-b}\right)\right)/C & b < |x| \leq r \\ 1 & r < |x| \end{cases},$$

$$\psi_{a,b,r}(x) = \begin{cases} x & |x| \leq a \\ a \operatorname{sign}(x) & a < |x| \leq b \\ a \operatorname{sign}(x) \frac{r-|x|}{r-b} & b < |x| \leq r \\ 0 & r < |x| \end{cases},$$

where  $C := \rho(\infty) = \rho(r) = \frac{a}{2}(2b - a + (r - b)) = \frac{a}{2}(b - a + r)$ .

As per our standardization,  $\psi$  has slope 1 in the center. The slope of the redescending part ( $x \in [b, r]$ ) is  $-a/(r - b)$ . If it is set to  $-\frac{1}{2}$ , as recommended sometimes, one has

$$r = 2a + b.$$

Here however, we restrict ourselves to  $a = 1.5k$ ,  $b = 3.5k$ , and  $r = 8k$ , hence a redescending slope of  $-\frac{1}{3}$ , and vary  $k$  to get the desired efficiency or breakdown point.

The constant  $k$  for 95% efficiency of the regression estimator is 0.9016 and the one for a breakdown point of 0.5 of the S-estimator is 0.212.

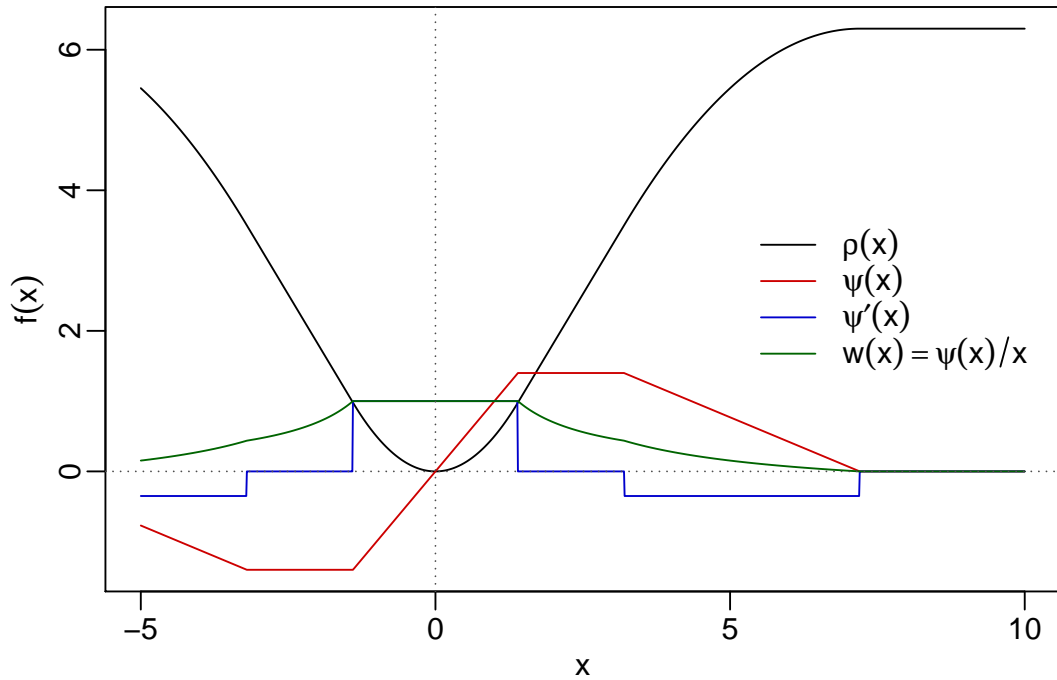


Figure 3: Hampel family of functions using tuning parameters  $0.902 \cdot (1.5, 3.5, 8)$ .

## 2.3 GGW

The Generalized Gauss-Weight function, or *ggw* for short, is a generalization of the Welsh  $\psi$ -function (below). In [Koller and Stahel \(2011\)](#) it is defined as,

$$\psi_{a,b,c}(x) = \begin{cases} x & |x| \leq c \\ \exp\left(-\frac{1}{2} \frac{(|x|-c)^b}{a}\right) x & |x| > c, \end{cases}.$$

The constants for 95% efficiency of the regression estimator are  $a = 1.387$ ,  $b = 1.5$  and  $c = 1.063$ . The constants for a breakdown point of 0.5 of the S-estimator are  $a = 0.204$ ,  $b = 1.5$  and  $c = 0.296$ .

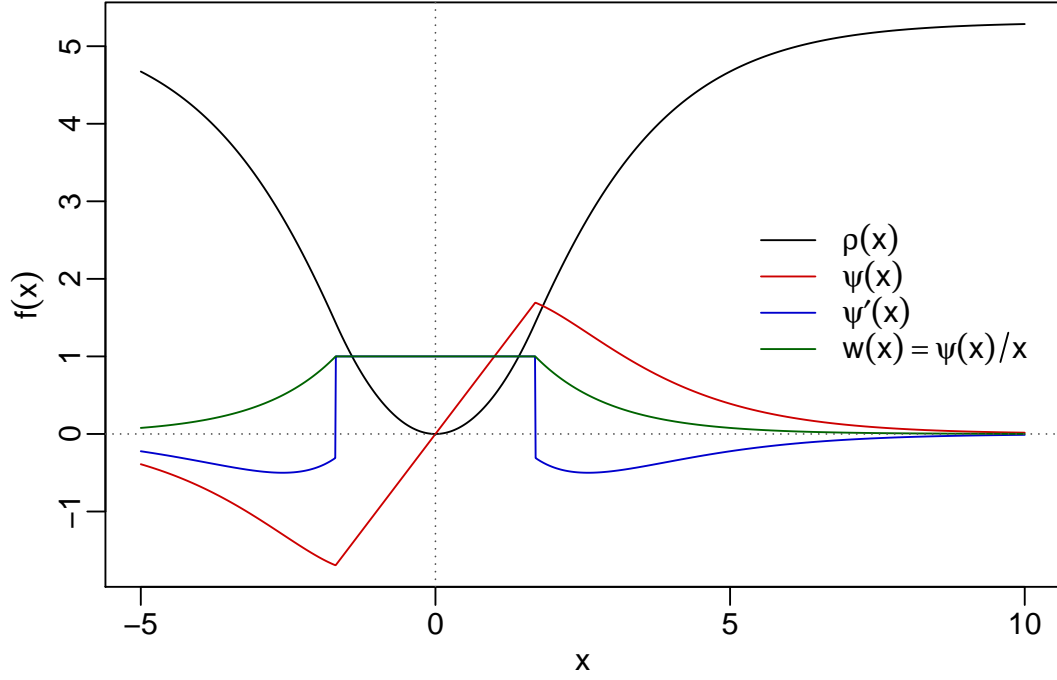


Figure 4: GGW family of functions using tuning parameters  $a = 1.387$ ,  $b = 1.5$  and  $c = 1.063$ .

## 2.4 LQQ

The “linear quadratic quadratic”  $\psi$ -function, or *lqq* for short, was proposed by [Koller and Stahel \(2011\)](#). It is defined as,

$$\psi_{b,c,s}(x) = \begin{cases} x & |x| \leq c \\ \text{sign}(x) \left( |x| - \frac{s}{2b} (|x| - c)^2 \right) & c < |x| \leq b + c \\ \text{sign}(x) \left( c + b - \frac{bs}{2} + \frac{s-1}{a} \left( \frac{1}{2}\tilde{x}^2 - a\tilde{x} \right) \right) & b + c < |x| \leq a + b + c \\ 0 & \text{otherwise,} \end{cases}$$

where  $\tilde{x} = |x| - b - c$  and  $a = (bs - 2b - 2c)/(1 - s)$ . The parameter  $c$  determines the width of the central identity part. The sharpness of the bend is adjusted by  $b$  while the maximal rate of descent is controlled by  $s$  ( $s = 1 - |\min_x \psi'(x)|$ ). The length  $a$  of the final descent to 0 is determined by  $b$ ,  $c$  and  $s$ .

The constants for 95% efficiency of the regression estimator are  $b = 1.473$ ,  $c = 0.982$  and  $s = 1.5$ . The constants for a breakdown point of 0.5 of the S-estimator are  $b = 0.402$ ,  $c = 0.268$  and  $s = 1.5$ .

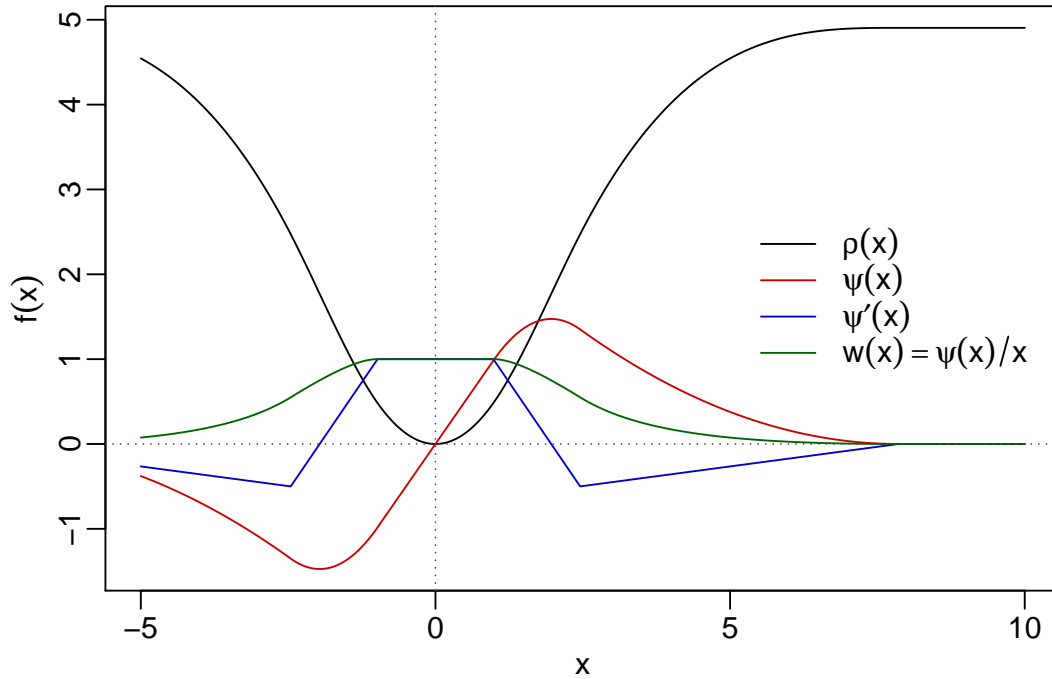


Figure 5: LQQ family of functions using tuning parameters  $b = 1.473$ ,  $c = 0.982$  and  $s = 1.5$ .

## 2.5 Optimal

The optimal  $\psi$  function as given by [Maronna et al. \(2006, Section 5.9.1\)](#),

$$\psi_c(x) = \text{sign}(x) \left( -\frac{\varphi'(|x|) + c}{\varphi(|x|)} \right)_+,$$

where  $\varphi$  is the standard normal density,  $c$  is a constant and  $t_+ := \max(t, 0)$  denotes the positive part of  $t$ .

The constant for 95% efficiency of the regression estimator is 1.060 and the constant for a breakdown point of 0.5 of the S-estimator is 0.405.

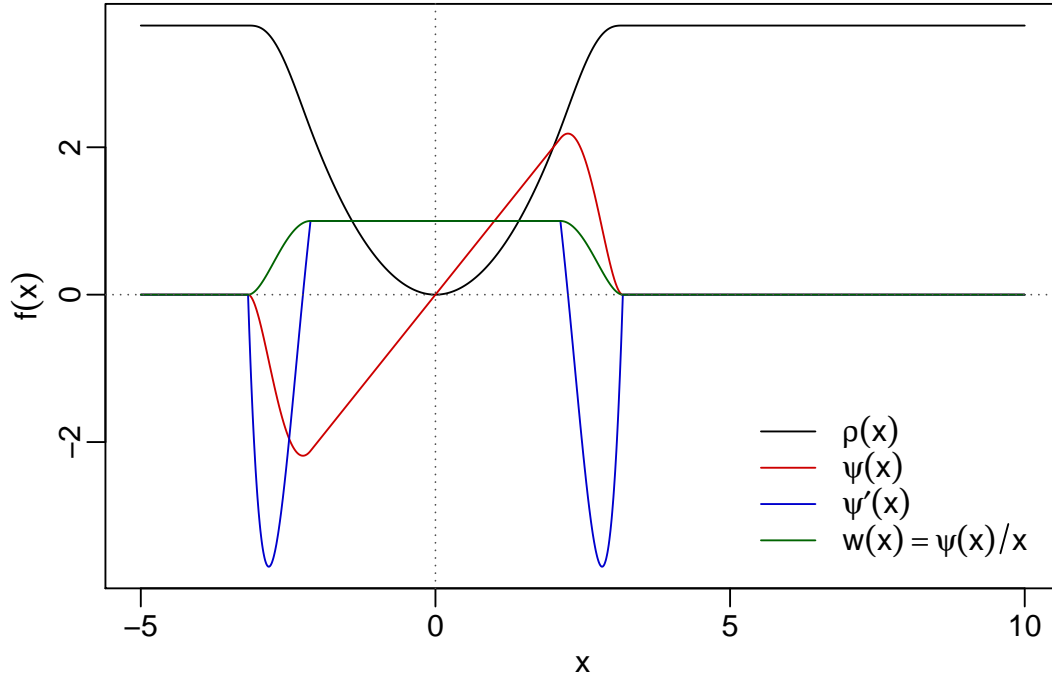


Figure 6: ‘Optimal’ family of functions using tuning parameter  $c = 1.06$ .

## 2.6 Welsh

The Welsh  $\psi$  function is defined as,

$$\begin{aligned}\tilde{\rho}_k(x) &= 1 - \exp(-(x/k)^2/2) \\ \psi_k(x) &= k^2 \tilde{\rho}'_k(x) = x \exp(-(x/k)^2/2) \\ \psi'_k(x) &= (1 - (x/k)^2) \exp(-(x/k)^2/2)\end{aligned}$$

The constant  $k$  for 95% efficiency of the regression estimator is 2.11 and the constant for a breakdown point of 0.5 of the S-estimator is 0.577.

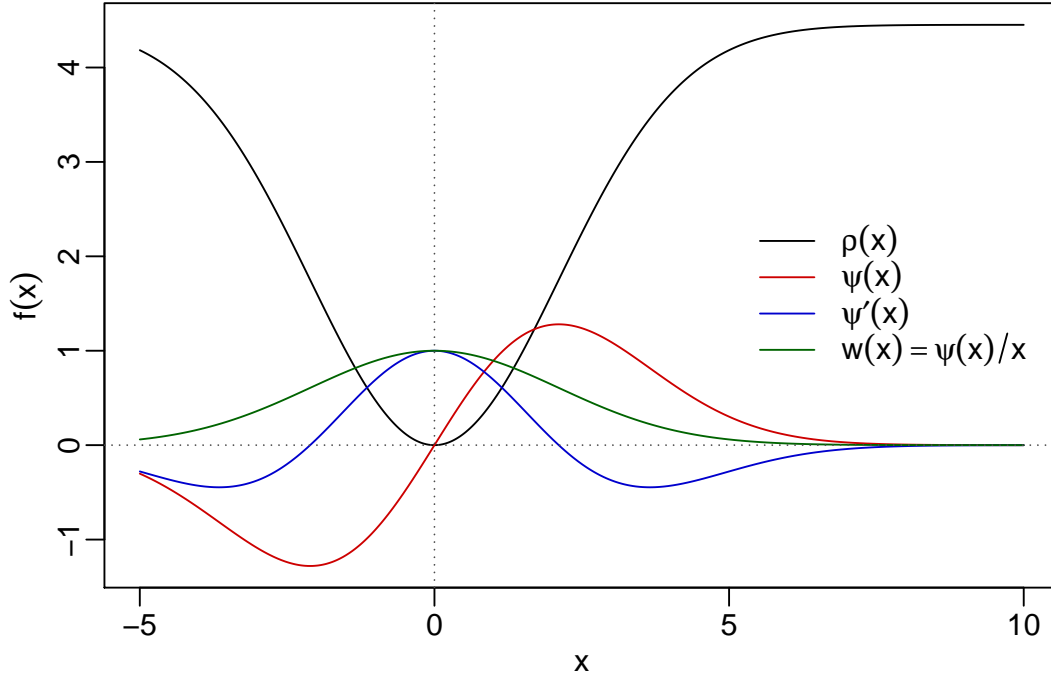


Figure 7: Welsh family of functions using tuning parameter  $k = 2.11$ .

## References

- Hampel, F., E. Ronchetti, P. Rousseeuw, and W. Stahel (1986). *Robust Statistics: The Approach Based on Influence Functions*. N.Y.: Wiley.
- Huber, P. J. (1964). Robust estimation of a location parameter. *Ann. Math. Statist.* 35, 73–101.
- Koller, M. and W. A. Stahel (2011). Sharpening wald-type inference in robust regression for small samples. *Computational Statistics & Data Analysis* 55(8), 2504–2515.
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